## Quiz:

a) It helps in having less instruction cachemisses.
b) It enables other optimizations, for example scalar replacement or reassociation.
c) It enables better instruction scheduling.

Pick the true statements [ , ].

## 2. Consider the following code:

double * func (const double N, const double *x, int size) \{
for ( $i=1, i$ < size; $i++$ )
$x[i]=(x[i] / s i z e){ }^{*} N$;
\}
The previous loop can be optimized as follows:

```
double * func (const double N, const double *x, int size) {
double tmp = N/size;
for (i=1, i < size; i++)
x[i] = x[i] * tmp;
}
```

Does compiler perform this optimization or not? Explain?
3. A GPU SM can load and store to and from (circleall that apply): [ ]
a) the GPU's device memory (on-board, off-chip)
b) the SM's local shared memory (on-chip)
c) the shared memories of other SM's
d) the L1 caches of other SMs
4. GPU thread divergence happens if (circle one):
[ ]
[1m]
a) different SMs execute different code
b) different thread blocks in one SM execute different code
c) different warps in one thread block execute different code
d) none of the above
e) all of the above
5. The code below was optimized in different ways resulting in versions v1 and v2. Both versions were tested on arrays of different sizes in the same computer. When v1 was used to compute on arrays of size 2000, the execution time was 64,000 cycles. When v2 was used when arrays of size 100 , the execution time was 4000 cycles. Which version do you think is better optimized? Justify your answer.
[2m]

```
for (inti= 0; i < size; i++){
C[i] = sqrt(A[i])+sqrt(B[i]);
}
```

6. Does a commercial compiler (icc) with higher optimization flags vectorize this loop? If not why? If so, how? [3m]
```
loc=maxint;
for (i=0; i<n; i++)
    if x[i]<0 {
        loc=i;
        break;
    }
```

7. Optimize the cache performance of the following code. Do not parallelizeit. Do not consider prefetching nor TLB behavior. You can assume that none of the operations overflow. Ass ume that $N$ and $M$ are extremely large powers of 2 . Assume that $A[], B[]$, and $C[]$ are integer arrays, and that an int is 4B.
```
for (i=0;i<N;i++)
    for (j=0;j<M;j++)
A[i] += B[j][j] * C[i];
```

8. a) The following data structure Data 2 is used to store one million samples of $(x, y, z) 3 D$ positioning data. How many bytes of memory will Data 2 occupy?
```
struct mystruct {
    int x; // 4
    int y; // 4
    int z; // 4
} Data2[1000000];
```

b) How many bytes of memory will the following alternative data structure Data3 occupy?

```
struct mystruct {
    int x[1000000]; // int is 4
    int y[1000000]; // int is 4
    int z[1000000]; // int is 4
    } Data3;
```

c) Data2 and Data3 above can both be used to store the same set of data, but would have different layouts in memory. If you were asked to write code to compute the distance from the origin of ( $x, y, z$ ) for 1000 randomly-selected samples, which of Data 2 or Data 3 would be the preferred data structure and why is it better than the alternative?
d) If you were asked to write code to compute the mean of $y$ across all million values, which of Data 2 or Data 3 would be the preferred data structure and why?
9. Generally, in which case would function inlining be leastlikely to harm per formance: A) a large function called from many locations; B) a large function called from a few locations; C) a small function called frommany locations; D) a small function called froma few locations. [ ]
11. Tiling: Given this machine:
$1^{\text {st }}$ level cache
[3m]
128B cacheblocks
8 -way set associative
16 sets,
Page size: $\mathbf{8 K B}$,
TLB: fully associative, 128 entries

If you were to tile the following code
// assume D[] is already initialized to zeros

```
void mmmc(int A[], int B[], int C[], int D[], int n){
for (i=0;i<n;i++){
for (j=0;j<n;j++) {
for (k=0;k<n;k++)
D[i*n+j] += A[i*n+k] * B[k*n+j] * C[i*n+j];
            }
            }
        }
```

Ignoring storage for instructions and small variables, and ass uming that there are no unlucky conflict misses (only capacity misses), what is the largest tile size $T$ (in number of elements, not bytes) that you can use to tile to minimize misses for the firstlevel data cache?

Name 8 optimizations that you would hope your compiler would do to this code. For each, give the formal name of the optimization and very briefly describe which variable(s) or code parts it will modify/improve and how. The first answer of 8 is given as an example.

1: $x=5$;
2: $y=2$;
3: debug $=0$;
4: $\mathrm{z}=\mathrm{x}+\mathrm{y}$;
5:
6: for ( $\mathrm{i}=0 ; \mathrm{i}<100 ; \mathrm{i}++$ ) $\{$
7: $m+=i^{*} x+y ;$
8: $n=z^{*} y$;
9: A[i] += A[m];
10:
11: if (debug)\{
12: printf("m: \%d\n",m);
13: \}
14: $\mathrm{q}+=\mathrm{i}^{*} \mathrm{x}$;
15:\}
16:
17:printf("result: \%d \%d \%d \%d \%d \%d\n",m,n,q,x,y,z);

ANSWERS:
constant propagation:line4 changed to $\mathrm{z}=5+2$
[OR]
13. The following C program is run (with no optimizations) on a processor with a direct-mapped cachethat has eight-word (32-byte) blocks and holds 256 words of data:

```
int i,j,c,stride,array[512];
for(i=0; i<10000; i++)
    for (j=0; j<512; j+=stride)
        c += i%(array[j]);
```

If we consider only the cache activity generated by references to the array and we assume that integers are words, what possible miss rates (there may be multiple) can we expect

1. if stride $=256$ ?
2. if stride $=255$ ?

Explain your answers clearly in a few sentences.

